

Independent Graduate Modules, one 21 hours module per week (3 ECTS)

Deadline for early registration: - to the modules M01 to M06: ???

- to the modules M07 to M21: ???

M01 – MILAN 06/02/2023-10/02/2023	<i>The scenario approach: data science for systems, control, and machine learning</i>	Marco C. Campi, University of Brescia, Italy; Simone Garatti, Politecnico di Milano, Italy
M02 – PARIS-SACLAY 13/02/2023-17/02/2023	<i>Multi-agent optimization and learning: resilient and adaptive solutions</i>	Nicola Bastianello, KTH, Stockholm, Sweden; Ruggero Carli & Luca Schenato, Univ. di Padova, Italy
M03 – SEVILLE 20/02/2023-24/02/2023	<i>Stabilization of PDEs: application on transport and parabolic equations</i>	Swann Marx, CNRS, LS2N, Nantes, France; Christophe Prieur, CNRS, GIPSA-Lab, Grenoble, France
M04 – PARIS-SACLAY 06/03/2023-10/03/2023	<i>Nonlinear and data-driven model predictive control</i>	Frank Allgöwer, University of Stuttgart, Germany; Matthias A. Müller, Leibniz Univ. Hannover, Germany
M05 – AACHEN 13/03/2023-17/03/2023	<i>Networked model predictive control for multi-agent decision-making</i>	Bassam Allrifaae, RWTH Aachen University, Germany
M06 – L'AQUILA 20/03/2023-24/03/2023	<i>Stability and stabilisation of time-varying systems, focus on formation and consensus control</i>	Antonio Loria, CNRS, L2S, Paris-Saclay, France
M07 – PARIS-SACLAY 27/03/2023-31/03/2023	<i>Constrained discrete optimal control on Lie groups</i>	Debashish Chatterjee & Ravi Banavar, IIT Bombay, India
M08 – LUCCA 27/03/2023-31/03/2023	<i>Hybrid control systems</i>	Ricardo Sanfelice, Univ. of California at Santa Cruz, USA
M09 – BERLIN 03/04/2023-07/04/2023	<i>Port-Hamiltonian systems and physics-based control</i>	Arjan van der Schaft, Univ. of Groningen Netherlands; Dimitri Jeltsema, HAN University, Arnhem, Netherlands
M10 – PARIS-SACLAY 11/04/2023-14/04/2023	<i>Time-delay and sampled-data systems</i>	Emilia Fridman, Tel Aviv University, Israel; Pierdomenico Pepe, University of L'Aquila, Italy
M11 – EINDHOVEN 17/04/2023-21/04/2023	<i>Static and dynamic optimisation</i>	Alessandro Astolfi, Giordano Scarcioffi & Thulasi Mylvaganam, Imperial College, London, UK
M12 – PARIS-SACLAY 24/04/2023-28/04/2023	<i>Nonsmooth dynamical systems: analysis, applications, stability and control</i>	Bernard Brogliato, INRIA, Grenoble, France; Aneel Tanwani, CNRS, LAAS, Toulouse, France
M13 – SEVILLE 02/05/2023-05/05/2023	<i>LMI for optimization and control</i>	Didier Henrion, CNRS, LAAS, Toulouse, France
M14 – PARIS-SACLAY 09/05/2023-12/05/2023	<i>Introduction to nonlinear systems &amp; control</i>	Hassan K. Khalil, Michigan State University, USA
M15 – SEVILLE 15/05/2023-19/05/2023	<i>Explicit methods for the control and the estimation of systems modeled by partial differential equations</i>	Arthur J. Krener, Naval Postgraduate School, Monterey, CA, USA; Miroslav Krstic, U. of California, San Diego, USA; Rafael Vazquez Valenzuela, U. of Seville, Spain
M16 – ROME 22/05/2023-26/05/2023	<i>Control of soft and articulated elastic robots</i>	Alessandro De Luca, Sapienza Università di Roma, Italy; Cosimo Della Santina, TU Delft, Netherlands
M17 – DELFT 22/05/2023-26/05/2023	<i>Multi-agent control under spatiotemporal logic constraints</i>	Lars Lindemann, University of Southern California, USA; Dimos Dimarogonas, KTH, Sweden
M18 – LONDON 05/06/2023-09/06/2023	<i>Learning to control</i>	Simone Formentin, Politecnico di Milano, Italy
M19 – CAGLIARI 05/06/2023-09/06/2023	<i>An overview on observer design methods for nonlinear systems</i>	Vincent Andrieu, & Daniele Astolfi, CNRS, Université de Lyon, France; Pauline Bernard, Mines ParisTech, France
M20 – PARIS 12/06/2023-16/06/2023	<i>Dynamical modeling, estimation, and control of open quantum systems</i>	Nina Amini, CNRS, L2S, Paris-Saclay, France; Pierre Rouchon, Mines ParisTech, France
M21 – BOLOGNA 12/06/2023-16/06/2023	<i>Distributed optimization for cooperative robotics and decision making: theory, numerical methods and toolboxes</i>	Giuseppe Notarstefano & Ivano Notarnicola; University of Bologna, Bologna, Italy
M22 – ZURICH 26/06/2023-30/06/2023	<i>Learning-based predictive control</i>	Melanie Zeilinger, ETH Zurich, Switzerland; Lorenzo Fagiano, Politecnico di Milano, Italy; Lukas Hewing, Sener Aerospace, Spain
M23 – PARIS-SACLAY 26/06/2023-30/06/2023	<i>Output feedback stabilisation and regulation for nonlinear systems</i>	Lorenzo Marconi & Michelangelo Bin, DEI - University of Bologna, Bologna, Italy

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